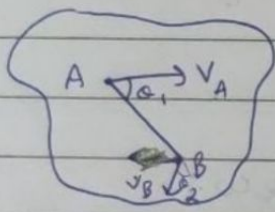


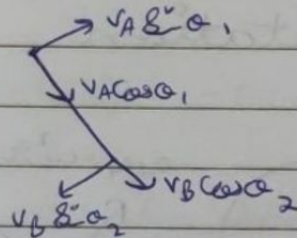
# Rotation

## # Rigid body.

- Rigid body is a system of particles in which distance b/w each pair of particles don't vary with time.



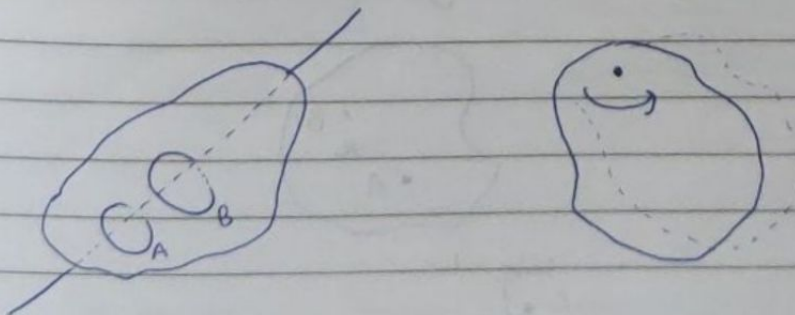
Rigid body.



- $v_A \cos \theta_1 = v_B \cos \theta_2$
- w.r.t any particle motion of other particle is circular

## # Rotation

- A rigid body is said to be in pure rotation if every particle of the body moves in a circle and centers of all circles lie on a straight line called axis of rotation.
- All points in body which are fixed to axis of rotation turn through the same angle in same time interval.





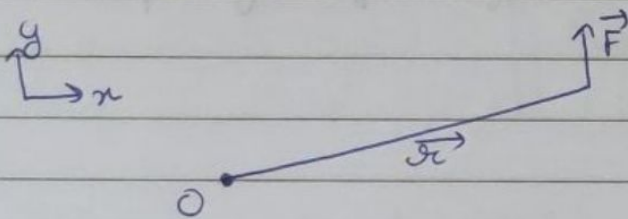
# # TORQUE

→ It is moment of force

→  $\vec{\tau} = \vec{r} \times \vec{F}$

→  $\vec{\tau} = \frac{d\vec{L}}{dt}$  = Rate of change of angular momentum.

→ for finding direction we use right hand rule. from  $\vec{r} \times \vec{F}$  right hand thumb shows the direction of axis along which  $\tau$  acts and right fingers of right hand curl in direction of motion that torque tends to cause.

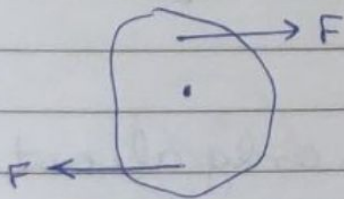


Axis along which  $\tau$  acts is along  $\hat{k}$ . Rotates about O in anti-clockwise sense.

# # Force Couple system.

→ Two equal and opposite forces whose lines of action don't coincide makes a couple.

eg



$\tau$  about any point in a couple system remains same.

## # Angular Momentum

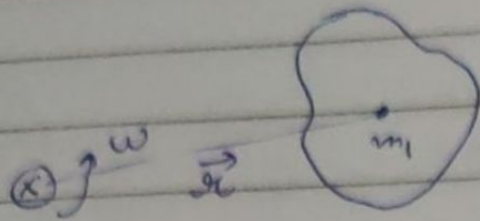
→ It is defined as moment of linear momentum

$$\vec{L} = \vec{r} \times \vec{p}$$

→  $L$  has a direction same as that of  $\omega$

→ Sometimes in  $\Omega$ , angular momentum magnitude remain same but direction is varying. Beware of such  $\Omega$ .





$$dL = m_1 \vec{r} \times \vec{p}$$

$$dL = \vec{r} \times (m_1 \vec{\omega} \times \vec{r})$$

$$dL = m_1 (\vec{r}^2 \vec{\omega} - (\vec{\omega} \cdot \vec{r}) \vec{r})$$

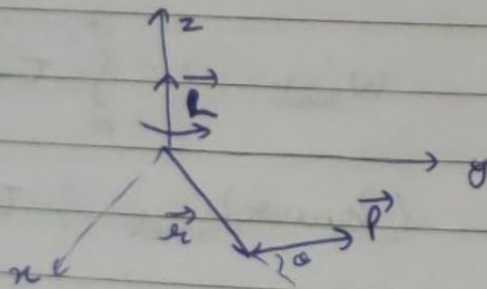
→ zero because  $\omega, v, r$  are  $\perp$  to each other

$$dL = m_1 r^2 \vec{\omega}$$

$$\vec{L} = \sum dL = \sum m_1 r^2 \vec{\omega} = \vec{\omega} \sum m_1 r^2$$

$$\boxed{\vec{L} = I \vec{\omega}} \rightarrow \text{only valid when } \vec{\omega} \text{ and } \vec{r} \text{ are } \perp \text{ to each other.}$$

### • Direction of Angular Momentum



direction of both  $\omega$  &  $L$  are same and given by right hand rule.

||



The particle  $P$  is executing circular motion. Is Angular Momentum No.