

$$\sum_{i \in \{A, B\}} T_{\text{sys}_i} \cdot a_{\text{sys}_i} \cdot \cos \theta_i = 0$$

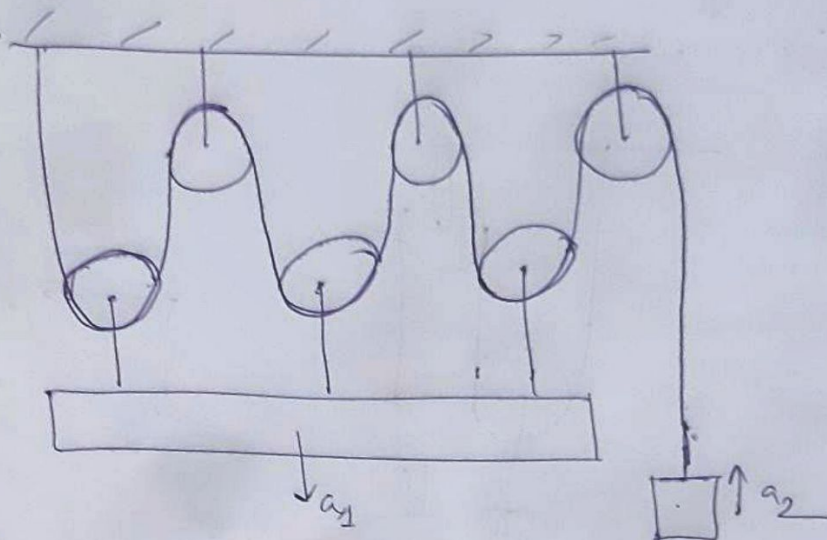
where A, B are systems,

$$\Rightarrow (2T a_A \cos 180) + (T a_B \cos 0) = 0$$

$$\Rightarrow -2T a_A + T a_B = 0$$

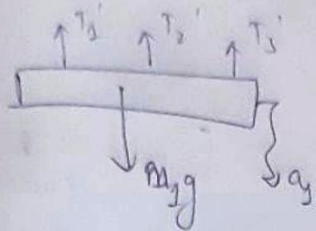
$$\Rightarrow \boxed{2a_A = a_B} \rightarrow \text{Same as earlier.}$$

4 (Easy)



Strings and pulleys are massless and frictionless. Relation between acceleration of the block (a_1 & a_2):

System - 1



Concepts Used

1. constraint Relation
2. Equilibrium

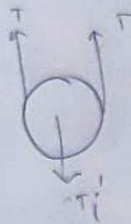
Formulae Used

1. Trick mentioned before.

$$m_1 g - \sum_{i=1}^3 T_i' = m_1 a_1$$

← ①

For each *i*th pulley :-



Since pulley is massless

$$\Rightarrow T_i' = 2T$$

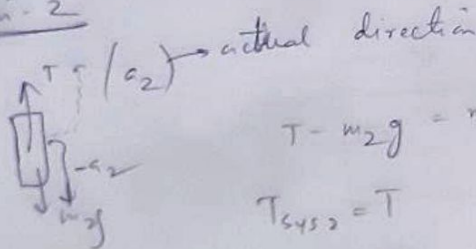
$$\Rightarrow \text{Eq ① changes to } m_1 g - 6T = m_1 a_1$$

$$\Rightarrow T_{\text{sys1}} = 6T$$

$$a_{\text{sys1}} = a_1$$

$$\theta = 180^\circ$$

System - 2



$$T - m_2 g = m_2 a_2$$

$$T_{\text{sys2}} = T$$

$$a_{\text{sys2}} = a_2$$

$$\theta = 0^\circ$$

~~Assup~~ Applying the theorem :-

$$\sum_{i=1}^2 T_{\text{sys}i} \cdot a_{\text{sys}i} \cos \theta_i = 0$$

$$\Rightarrow -6T a_1 + T a_2 = 0 \quad \left[\begin{array}{l} \text{since } \cos 180^\circ = -1 \\ \cos 0^\circ = 1 \end{array} \right]$$

$$\Rightarrow \boxed{6a_1 = a_2}$$

(Mark)

Three equal weights of mass 2 kg each