

* DAMPED SIMPLE HARMONIC MOTION

if damping force is

$$F_d = -b\vec{v}$$

so, our equation becomes

$$m \frac{d^2x}{dt^2} + b \frac{dx}{dt} + kx = 0$$

OR $x(t) = A e^{-\frac{bt}{2m}} \cos(\omega' t + \phi)$

where,

$$\omega' = \sqrt{\frac{k}{m} - \frac{b^2}{4m^2}}$$

Total Mechanical Energy

$$E(t) = \frac{1}{2} k A^2 e^{-\frac{bt}{m}}$$

* FORCED OSCILLATION (WITH DAMPING)

Taking force, $F = F_0 \cos \omega_d t$

$\omega_d \equiv$ driven frequency

Equation becomes -

$$m \frac{d^2x}{dt^2} + b \frac{dx}{dt} + kx = F_0 \cos \omega_d t$$

so,

$$x = A \cos(\omega_d t + \phi)$$

$$A = \frac{F_0}{\left[m^2(\omega^2 - \omega_d^2)^2 + \omega_d^2 b^2 \right]^{1/2}}$$

and $\tan \phi = \frac{-v_0}{\omega_d x_0}$ v_0 & x_0 are
at time $t=0$

(a) Small Damping (b is small)

$$A = \frac{F_0}{m(\omega^2 - \omega_d^2)} \quad \text{i.e. } \omega b \text{ is small.}$$

(b) Driving Frequency ω closer to ω_d

$$A = \frac{F_0}{\omega_d b}$$

Resonance occurs when $(\omega = \omega_d)$.

Torsional Pendulum

Torque in this case

\propto (angle the wire is rotated)

which gives

$$\tau \propto \theta \Rightarrow \tau = -C\theta \quad \left\{ \begin{array}{l} C \text{ is torsional} \\ \text{constant} \end{array} \right.$$

$$\text{so, } \tau = I\alpha = -C\theta$$

$$\Rightarrow \alpha = -\left(\frac{C}{I}\right)\theta \quad \text{which gives}$$
$$\omega^2 = \frac{C}{I}$$

$$\text{so, } T = 2\pi \sqrt{\frac{I}{C}}$$

$I \equiv$ Moment of inertia about vertical axis.