THREE DIMENSIONAL GEOMETRY

11.1 Overview

- 11.1.1 Direction cosines of a line are the cosines of the angles made by the line with positive directions of the co-ordinate axes.
- **11.1.2** If *l*, *m*, *n* are the direction cosines of a line, then $l^2 + m^2 + n^2 = 1$
- 11.1.3 Direction cosines of a line joining two points $P(x_1, y_1, z_1)$ and $Q(x_2, y_2, z_2)$ are

$$\frac{x_2 - x_1}{PQ}$$
, $\frac{y_2 - y_1}{PQ}$, $\frac{z_2 - z_1}{PQ}$,

where
$$PQ = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

- **11.1.4** Direction ratios of a line are the numbers which are proportional to the direction cosines of the line.
- 11.1.5 If l, m, n are the direction cosines and a, b, c are the direction ratios of a line,

then
$$l = \frac{\pm a}{\sqrt{a^2 + b^2 + c^2}}; m = \frac{\pm b}{\sqrt{a^2 + b^2 + c^2}}; n = \frac{\pm c}{\sqrt{a^2 + b^2 + c^2}}$$

- **11.1.6** Skew lines are lines in the space which are neither parallel nor interesecting. They lie in the different planes.
- 11.1.7 Angle between skew lines is the angle between two intersecting lines drawn from any point (preferably through the origin) parallel to each of the skew lines.
- 11.1.8 If l_1 , m_1 , n_1 and l_2 , m_2 , n_2 are the direction cosines of two lines and θ is the acute angle between the two lines, then

$$\cos\theta = |l_1 l_2 + m_1 m_2 + n_1 n_2|$$

11.1.9 If a_1 , b_1 , c_1 and a_2 , b_2 , c_2 are the directions ratios of two lines and θ is the acute angle between the two lines, then

$$\cos \theta = \frac{a_1 a_2 + b_1 b_2 + c_1 c_2}{\sqrt{a_1^2 + a_2^2 + a_3^2} \cdot \sqrt{b_1^2 + b_2^2 + b_3^2}}$$

- 11.1.10 Vector equation of a line that passes through the given point whose position vector is a and parallel to a given vector b is $r=a+\lambda b$.
- **11.1.11** Equation of a line through a point (x_1, y_1, z_1) and having directions cosines l, m, n (or, direction ratios a, b and c) is

$$\frac{x-x_1}{l} = \frac{y-y_1}{m} = \frac{z-z_1}{n}$$
 or $\left(\frac{x-x_1}{a} = \frac{y-y_1}{b} = \frac{z-z_1}{c}\right)$.

- 11.1.12 The vector equation of a line that passes through two points whose positions vectors are a and b is $r=a+\lambda(b-a)$.
- 11.1.13 Cartesian equation of a line that passes through two points (x_1, y_1, z_1) and (x_2, y_2, z_2) is

$$\frac{x-x_1}{x_2-x_1} = \frac{y-y_1}{y_2-y_1} = \frac{z-z_1}{z_2-z_1}.$$

11.1.14 If θ is the acute angle between the lines $r = a_1 + \lambda b_1$ and $r = a_2 + \lambda b_2$, then

$$\theta$$
 is given by $\cos \theta = \frac{|b_1.b_2|}{|b_1||b_2|}$ or $\theta = \cos^{-1} \frac{|b_1.b_2|}{|b_1||b_2|}$.

- 11.1.15 If $\frac{x-x_1}{l_1} = \frac{y-y_1}{m_1} = \frac{z-z_1}{n_1}$ and $\frac{x-x_2}{l_1} = \frac{y-y_2}{m_2} = \frac{z-z_2}{n_2}$ are equations of two lines, then the acute angle θ between the two lines is given by $\cos\theta = |l_1 l_2 + m_1 m_2 + n_1 n_2|$.
- **11.1.16** The shortest distance between two skew lines is the length of the line segment perpendicular to both the lines.
- 11.1.17 The shortest distance between the lines $r = a_1 + \lambda b_1$ and $r = a_2 + \lambda b_2$ is

$$\left| \frac{\left(b_1 \times b_2\right) \cdot \left(a_2 - a_1\right)}{\left|b_1 \times b_2\right|} \right|.$$

11.1.18 Shortest distance between the lines: $\frac{x-x_1}{a_1} = \frac{y-y_1}{b_1} = \frac{z-z_1}{c_1}$ and

$$\frac{x-x_2}{a_2} = \frac{y-y_2}{b_2} = \frac{z-z_2}{c_2}$$
 is

$$\frac{\begin{vmatrix} x_2 - x_1 & y_2 - y_1 & z_2 - z_1 \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix}}{\sqrt{(b_1 c_2 - b_2 c_1)^2 + (c_1 a_2 - c_2 a_1)^2 + (a_1 b_2 - a_2 b_1)^2}}$$

11.1.19 Distance between parallel lines $r = a_1 + \mu b$ and $r = a_2 + \lambda b$ is

$$\left| \frac{b \times (a_2 - a_1)}{|b|} \right|.$$

11.1.20 The vector equation of a plane which is at a distance p from the origin, where \hat{n} is the unit vector normal to the plane, is $r \cdot \hat{n} = p$.

11.1.21 Equation of a plane which is at a distance p from the origin with direction cosines of the normal to the plane as l, m, n is lx + my + nz = p.

11.1.22 The equation of a plane through a point whose position vector is a and perpendicular to the vector n is (r-a).n=0 or r.n=d, where d=a.n.

11.1.23 Equation of a plane perpendicular to a given line with direction ratios a, b, c and passing through a given point (x_1, y_1, z_1) is $a(x - x_1) + b(y - y_1) + c(z - z_1) = 0$.

11.1.24 Equation of a plane passing through three non-collinear points (x_1, y_1, z_1) , (x_2, y_2, z_2) and (x_3, y_3, z_3) is

$$\begin{vmatrix} x - x_1 & y - y_1 & z - z_1 \\ x_2 - x_1 & y_2 - y_1 & z_2 - z_1 \\ x_3 - x_1 & y_3 - y_1 & z_3 - z_1 \end{vmatrix} = 0.$$

- 11.1.25 Vector equation of a plane that contains three non-collinear points having position vectors a, b, c is (r-a). $[(b-a)\times(c-a)]=0$
- 11.1.26 Equation of a plane that cuts the co-ordinates axes at (a, 0, 0), (0, b, 0) and (0, 0, c) is $\frac{x}{a} + \frac{y}{b} + \frac{z}{c} = 1$.
- 11.1.27 Vector equation of any plane that passes through the intersection of planes $r \cdot n_1 = d_1$ and $r \cdot n_2 = d_2$ is $(r \cdot n_1 d_1) + \lambda (r \cdot n_2 d_2) = 0$, where λ is any non-zero constant.
- **11.1.28** Cartesian equation of any plane that passes through the intersection of two given planes $A_1x + B_1y + C_1z + D_1 = 0$ and $A_2x + B_2y + C_2z + D_2 = 0$ is $(A_1x + B_1y + C_1z + D_1) + \lambda (A_2x + B_2y + C_2z + D_2) = 0$.
- 11.1.29 Two lines $r = a_1 + \lambda b_1$ and $r = a_2 + \lambda b_2$ are coplanar if $(a_2 a_1) \cdot (b_1 \times b_2) = 0$
- 11.1.30 Two lines $\frac{x x_1}{a_1} = \frac{y y_1}{b_1} = \frac{z z_1}{c_1}$ and $\frac{x x_2}{a_2} = \frac{y y_2}{b_2} = \frac{z z_2}{c_2}$ are coplanar if

$$\begin{vmatrix} x_2 - x_1 & y_2 - y_1 & z_2 - z_1 \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix} = 0,$$

11.1.31 In vector form, if θ is the acute angle between the two planes, $r \cdot n_1 = d_1$ and

$$r \cdot n_2 = d_2$$
, then $\theta = \cos^{-1} \frac{|n_1 \cdot n_2|}{|n_1| \cdot |n_2|}$

11.1.32 The acute angle θ between the line $r = a + \lambda b$ and plane $r \cdot n = d$ is given by

$$\sin \theta = \frac{\left|b \cdot n\right|}{\left|b\right| \cdot \left|n\right|}.$$

11.2 Solved Examples

Short Answer (S.A.)

Example 1 If the direction ratios of a line are 1, 1, 2, find the direction cosines of the line.

Solution The direction cosines are given by

$$l = \frac{a}{\sqrt{a^2 + b^2 + c^2}}, m = \frac{b}{\sqrt{a^2 + b^2 + c^2}}, n = \frac{c}{\sqrt{a^2 + b^2 + c^2}}$$

Here a, b, c are 1, 1, 2, respectively.

Here
$$a, b, c$$
 are 1, 1, 2, respectively. Therefore, $l = \frac{1}{\sqrt{1^2 + 1^2 + 2^2}}, m = \frac{1}{\sqrt{1^2 + 1^2 + 2^2}}, n = \frac{2}{\sqrt{1^2 + 1^2 + 2^2}}$

i.e.,
$$l = \frac{1}{\sqrt{6}}$$
, $m = \frac{1}{\sqrt{6}}$, $n = \frac{2}{\sqrt{6}}$ i.e. $\pm \left(\frac{1}{\sqrt{6}}, \frac{1}{\sqrt{6}}, \frac{2}{\sqrt{6}}\right)$ are D.C's of the line.

Example 2 Find the direction cosines of the line passing through the points P(2, 3, 5) and Q(-1, 2, 4).

Solution The direction cosines of a line passing through the points P (x_1, y_1, z_1) and Q (x_2, y_2, z_2) are

$$\frac{x_2 - x_1}{PQ}$$
, $\frac{y_2 - y_1}{PQ}$, $\frac{z_2 - z_1}{PQ}$.

Here
$$PQ = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

= $\sqrt{(-1 - 2)^2 + (2 - 3)^2 + (4 - 5)^2} = \sqrt{9 + 1 + 1} = \sqrt{11}$

Hence D.C.'s are